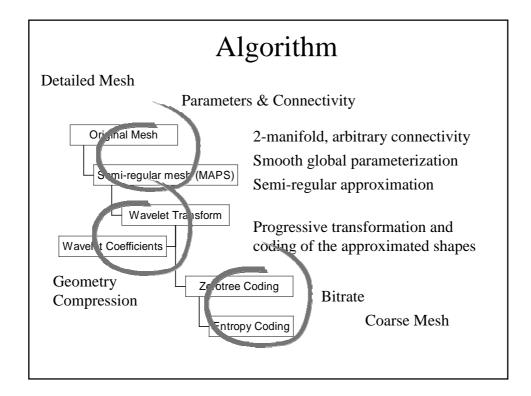
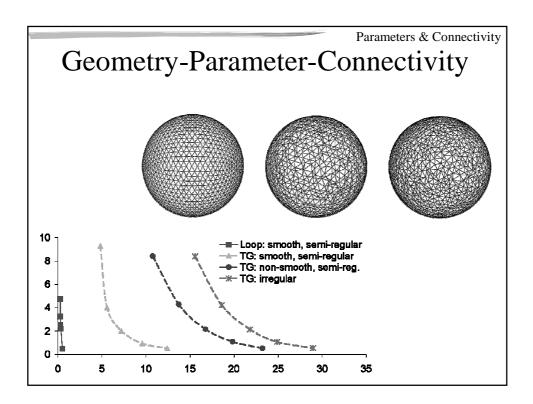
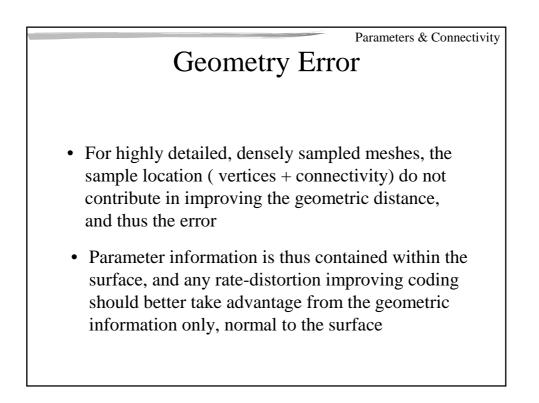


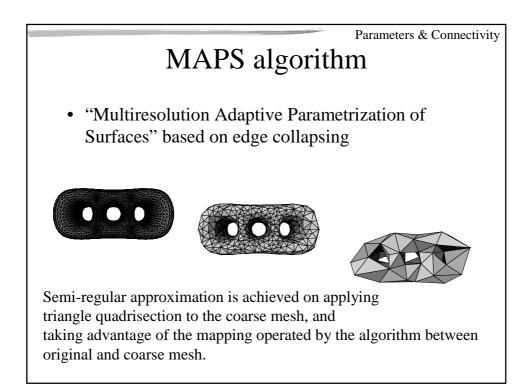


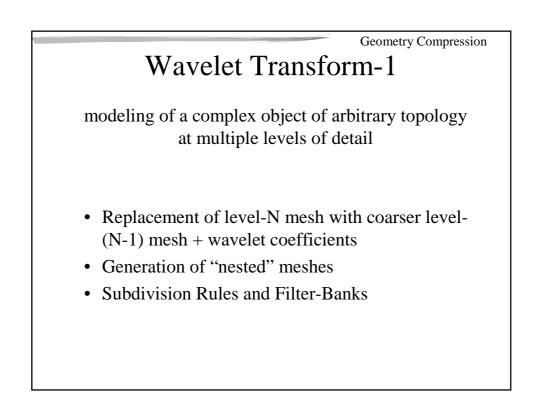
- Accuracy/ bit per vertex
- Definition of a Geometry Error
 - Measure of the geometric distance between 3D objects
- New Problems with Respect to Image Compression
 - No direct correspondence between original and compressed surface

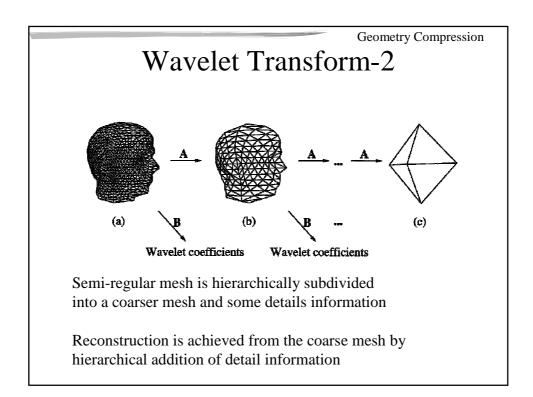


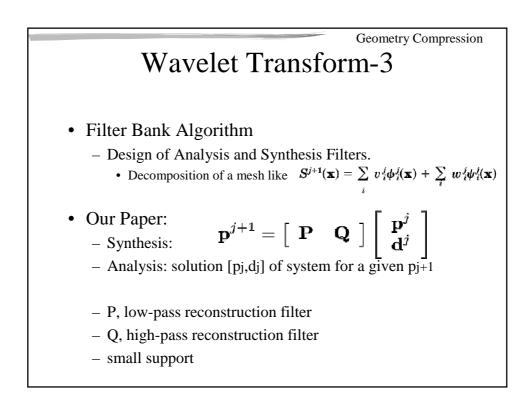


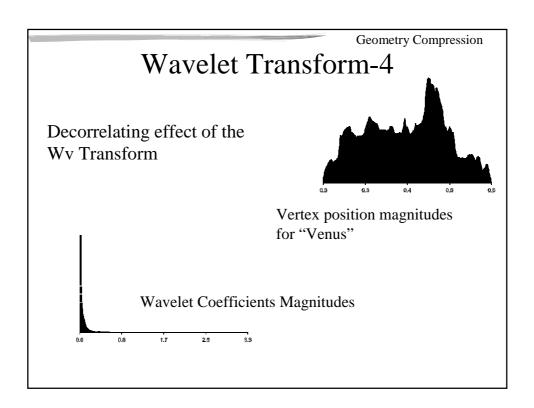


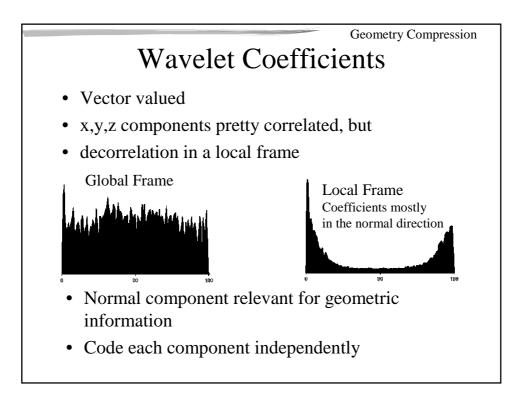


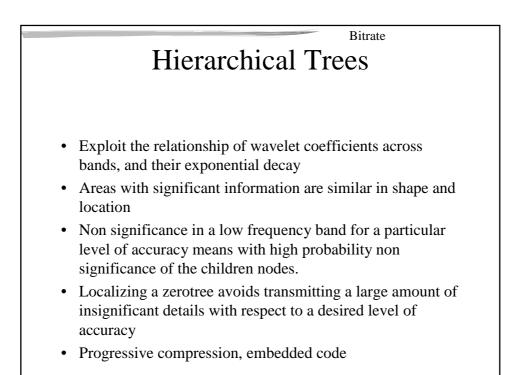


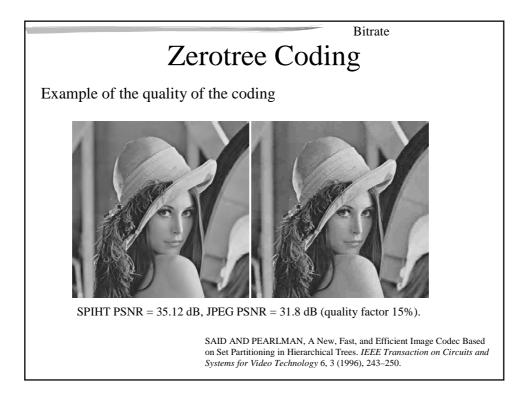


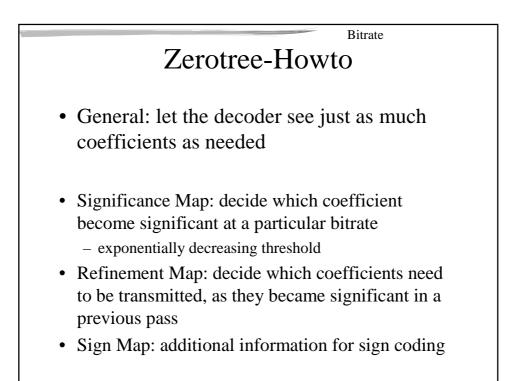


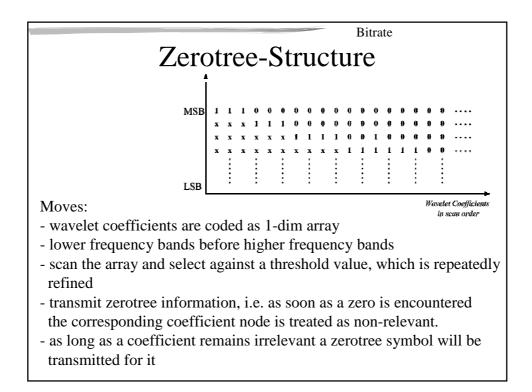


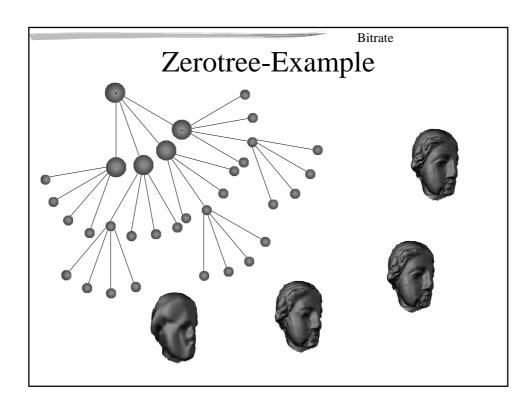


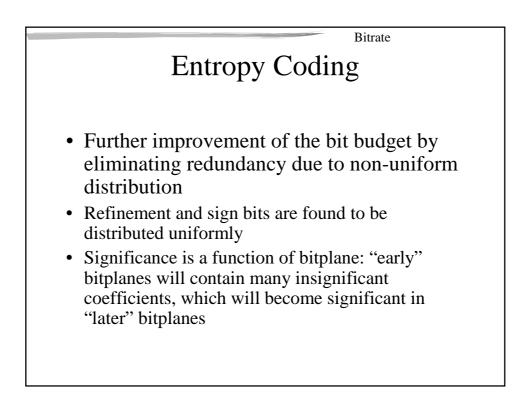


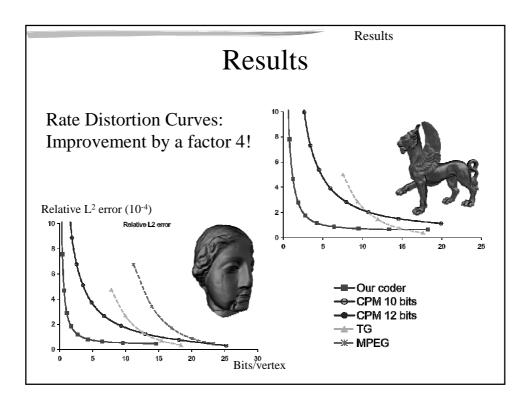


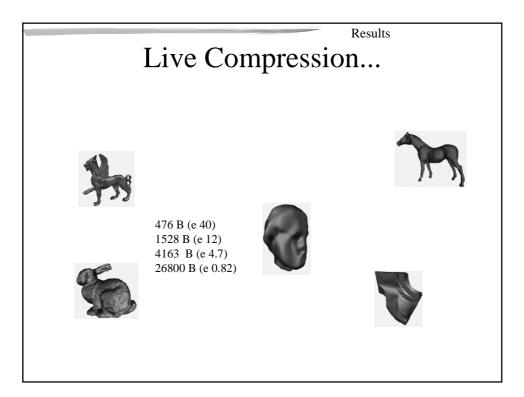






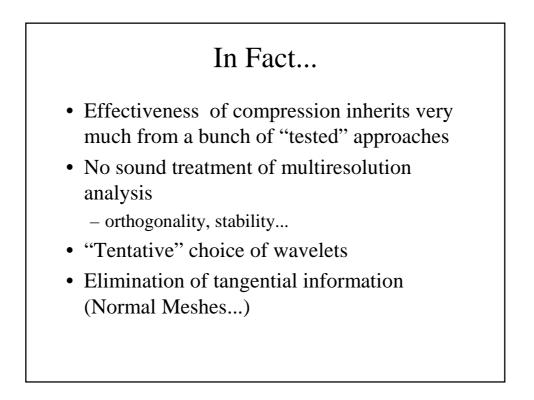


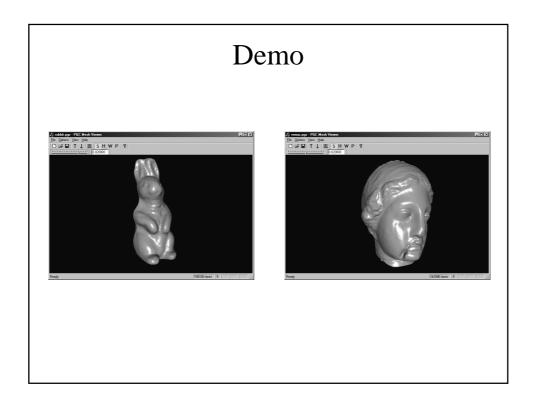


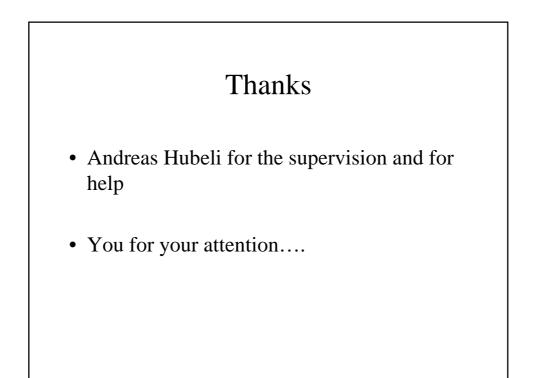


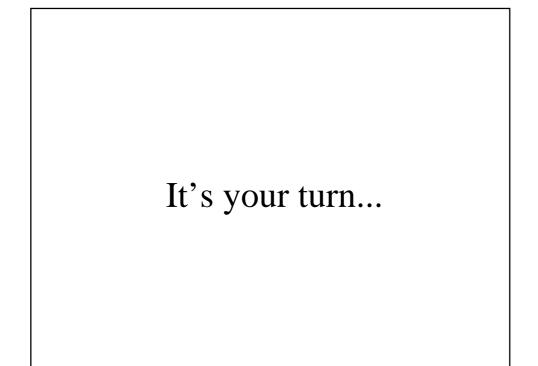
Conclusions

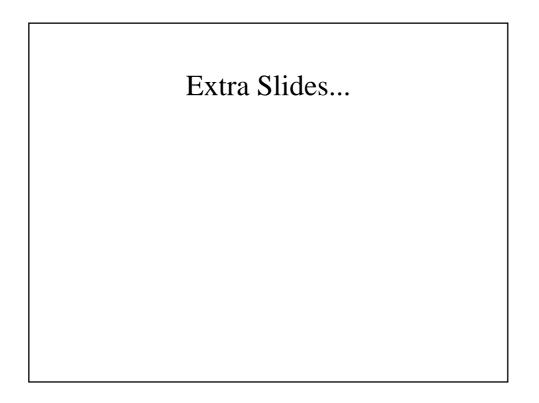
- Very effective compression algorithm – smooth appearance, low (hardware) strain
- Many details in very early stages of decompression
- Very fruitful distinction between parameters and geometry
- Still at the beginning of wavelet 3D model compression...











Geometry Compression Wavelet Transform-2 Ingredients of Multiresolution Analysis (Mallat and Meyer) : Existence of nested linear spaces and of an inner product relative to a subdivision rule. $V^0 \subset V^1 \subset V^2 \subset \cdots$ $W^j := \{f \in V^{j+1} | \langle f, g \rangle = 0 \quad g \in V^j\} \quad f^{j+1} = f^j + h^j$ Nested spaces are generated by translations and dilations of a single function, $\phi(x) \qquad \phi(x) = \sum_i p_i \phi(2x - i)$ $V^j := \operatorname{Span} \{ \phi(2^j x - i) | i = -\infty, \dots, \infty \}$ Subdivision Rules can be used to define such functions

Distance Function

• Euclidean Distance (L²) d(X,Y) between two surfaces X, Y

$$d(X,Y) = \left(\frac{1}{\operatorname{area}(X)}\int_{x\in X} d(x,Y)^2 dx\right)^{1/2}$$

• Symmetrize by taking the max of d(X,Y) and d(Y,X)